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April 1\textsuperscript{st}, 2010
Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation ([http://www.renesas.com](http://www.renesas.com))

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1. Abstract
   This document describes timer A operation in the programmable output mode.

2. Introduction
   The application example described in this document applies to the following MCUs:

   • MCUs: M16C/63 Group
     M16C/64A Group
     M16C/65 Group

   Careful evaluation is recommended before using the program described in this application note.
3. Programmable Output Mode

In programmable output mode, the timer outputs arbitrary low- and high-level width of pulse successively. The mode can be used in timer A1, A2 and A4. The high-level width of pulse can be set in the TAi register (i = 1, 2 or 4), and the low-level width of pulse can be set in the TAi1 register.

To change cycles or width of the output waveform, follow the instructions below.

1. Set the TAiOW bit to 0 (output waveform change disabled).
2. Write to the TAi register and/or the TAi1 register.
3. Set the TAiOW bit to 1 (output waveform change enabled).

The updated value is reloaded when the TAiOW bit is 1 (output waveform change enabled) at one cycle before the rising edge of the TAiOUT output (the falling edge when the POFSi bit is 1). The value before the update is reloaded when the TAiOW bit is 0 (output waveform change disabled). Figure 3.1 shows an example of programmable output.

**Figure 3.1 Example of Programmable Output**

- TAi register
- TAi1 register
- TAiOUT output
- One cycle before the rising edge of the TAiOUT output (reload decision timing)
- The value before updated is reloaded because TAiOW bit is 0 at the reload decision timing.
- The value after updated is reloaded because TAiOW bit is 1 at the reload decision timing.

---

i = 1, 2, 4
m1: Value assigned to TAi register for high-level width of pulse 1
n1: Value assigned to TAi1 register for low-level width of pulse 1
m2: Value assigned to TAi register for high-level width of pulse 2
n2: Value assigned to TAi1 register for low-level width of pulse 2
fj: Count source frequency

The above timing diagram assumes the following:
- The MR0 bit in the TAIMR register is 1 (pulse output).
- The POFSi bit in the TAPOFSi register is 0 (output waveform high-level active).
4. Application Example

4.1 Explanation of the Sample Program
In the sample program, two different pulses (pulse A and B) are output alternately and successively using programmable output mode of timer A. Timer values are updated in the interrupt process of timer A. Sample output waveform is output on the following conditions.
Count source: 8 MHz
Output waveform: High-level active
High-level width of pulse A: 8 ms      Low-level width of pulse A: 4 ms
High-level width of pulse B: 2 ms      Low-level width of pulse B: 6 ms

Figure 4.1 shows the output waveform of the sample program.

4.2 Configuration of the Sample Program
Table 4.1 lists the configuration of the application example.

<table>
<thead>
<tr>
<th>Item</th>
<th>Specification</th>
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<tbody>
<tr>
<td>Count source</td>
<td>Select from the following sources.</td>
</tr>
<tr>
<td></td>
<td>f1TIMAB, f2TIMAB, f8TIMAB, f32TIMAB, f64TIMAB, fC32, fOCO-F(1), or fOCO-S</td>
</tr>
<tr>
<td>Output polarity</td>
<td>Output polarity high-level active</td>
</tr>
<tr>
<td></td>
<td>Output polarity low-level active (output reversed)</td>
</tr>
<tr>
<td>Output waveform change</td>
<td>Change disabled</td>
</tr>
<tr>
<td></td>
<td>Change enabled</td>
</tr>
<tr>
<td>Count trigger</td>
<td>Write 1 to the TAiS bit in the TABSR register</td>
</tr>
<tr>
<td></td>
<td>Select by bits TAITGH to TAITGL</td>
</tr>
</tbody>
</table>

i = 1, 2, 4

Note:
1. Not available in the M16C/64A Group.
4.3 Operations of the Sample Program

(1) Timer Ai (i = 1, 2, 4) is set, a value of high-level width of pulse A (m1) is written in the TAi register and then a value of low-level width of pulse A (n1) is written in the TAi1 register.

(2) When the TAiS bit in the TABSR register is set to 1, the value of the TAi register is reloaded and the count is started. At the same time, the state of the TAiOUT pin is changed from low to high and then an interrupt request is generated.

(3) After the TAiOW bit is set to 0 in the interrupt process of timer Ai, a value of high-level width of pulse B (m2) in the TAi register and a value of low-level width of pulse B (n2) are written in the TAi1 register and then the TAiOW bit is set to 1.

(4) When the timer underflows, the value of the TAi1 register is reloaded and the count is continued. At the same time, the state of the TAiOUT pin is changed from high to low.

(5) When the timer underflows, the state of the TAiOUT pin is changed from low to high and an interrupt request is generated. Because the TAiOW bit is 1 at the reload decision timing, the values are reloaded after updated (m2, n2) and the count is started. (When the TAiOW bit is 0, the values before updated (m1, n1) are reloaded and the count is started.)

(6) After the TAiOW bit is set to 0 in the interrupt process of timer Ai, a value of high-level width of pulse A (m1) in the TAi register and a value of low-level width of pulse A (n1) are written in the TAi1 register and then the TAiOW bit set to 1.

(7) When the TAiS bit is set to 0, the count is stopped and then low-level is output to the TAiOUT pin.
Figure 4.2 shows operation example in programmable output mode.

![Figure 4.2 Operation Example in Programmable Output Mode](image)

The above timing diagram assumes the following:
- The MR0 bit in the TAiMR register is 1 (pulse output).
- The MR2 bit in the TAiMR register is 0 (The count trigger is the TAiS bit in the TABSR set to 1.).
- The POFSi bit in the TAPOFS register is 0 (output waveform high-level active).

Figure 4.2  Operation Example in Programmable Output Mode
### 5. Register Settings

Figure 5.1 and Figure 5.2 show procedure and value for setting register in programmable output mode of timer A1. Refer to a hardware manual of the MCU you use for more details on each register.

![Diagram](image_url)

**Figure 5.1  Procedure for Setting Register in Programmable Output Mode of Timer A (1/2)**
Figure 5.2  Procedure for Setting Register in Programmable Output Mode of Timer A (2/2)
6. **Sample Program**

A sample program can be downloaded from the Renesas Technology website. To download, click "Application Notes" in the left-hand side menu of the M16C Family page.

7. **Reference Documents**

Hardware Manual  
M16C/63 Group Hardware Manual  
M16C/64A Group Hardware Manual  
M16C/65 Group Hardware Manual  
The latest version of these documents can be downloaded from the Renesas Technology website.

Technical Update/Technical News  
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<th>Description</th>
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<tbody>
<tr>
<td>1.00</td>
<td>Feb 05, 2010</td>
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